The Future of AMRs Now Wide Open

ADLINK ROS 2 Solution







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The Future of AMRs Now Wide Open

The future of Automated Mobile Robots (AMRs) is now wide open, as they are due to revolutionize every sector. These intelligent machines can autonomously navigate and adapt to dynamic environments, performing tasks like material handling, package delivery, lawn mowing, and more. With proven value in enhancing productivity and safety, AMRs will become even smarter and more adaptable further down the road, expanding their applications to sectors beyond imaginable. Embrace AMRs and automation technologies, and you are in for a transformational treat in the coming years.

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Discover Our ROS 2 Robotic Controllers

The robotic controller is crucial in enabling an AMR to operate independently. Since it has to combine sensor data, decision-making algorithms, and task execution logic to navigate, interact with its environment, and carry out assigned tasks efficiently and safely, its effectiveness directly impacts the AMR system's overall performance, reliability, and adaptability. Hence, ADLINK has created the ROScube, a highly versatile and modular ROS 2 robotic controller family, and here are the three main series of ROScube:

ROX-58G-E

RQP-T37

ROScube-Pico TGL

Compact robotic controller powered by Intel[®] CPU for quick and easy development

ROScube-X

AI robotic controller powered by NVIDIA[®] Jetson™ for real-time Sensor Fusion

ROScube-I

ROX-59

RQI-58-E

Intelligent robotic controller powered by Intel[®] CPU for complex data processing

Solution Stack

The ROScube family is specially designed to seamlessly integrate with ROS 2 and its ecosystem. This guarantees a smoother development process and improved synergy between hardware and software.



Accelerate Your Success with ADLINK ROS 2 Solution

Benefits

We have years of experience in system and sensor integrations.



We are experts in edge AI platform and BSP customization.

NELRONSDK

We are proud to support startup developers with Neuron SDK for an accelerated PoC and implementation.

Service Flow



In-depth discussion over project details and requirements



Recommending a suitable edge AI platform (robotic controller)



Customer testing and feedback



Quick PoC and implementation

Key Components of a Sensor Fusion System

A sensor fusion system combines data from multiple sensors to provide an accurate understanding of the environment.

Key components of such a system include

- Crucial sensors: Cameras, LiDAR, radar, and more, capturing different types of data.
- Data preprocessing: Cleaning and organizing data for further processing.
- Sensor calibration: Ensuring proper alignment and synchronization.
- Sensor data fusion algorithms: Combining data and extracting valuable information using techniques such as Kalman filtering and particle filtering.
- Edge perception units and/or computational platforms: Effectively processing large amounts of data and flawlessly executing fusion algorithms.

ADLINK's ROScube robotic controller is known for its outstanding performance and power efficiency. The RQX-59 Series is the perfect edge perception system that offers Frame Sync for GMSL2 and FPD-Link III cameras, as well as customized BSPs. It has a comprehensive I/O interface and uses the Jetson AGX Orin module, designed to process sensor fusion data and execute fusion algorithms seamlessly. 3D LIDAR

Robotic Controller (RQX-59 Series)

360-Degree Camera

Mic & Speaker





Forklift Robot

Challenges & Requirements

- Covering a wide geographic area and transporting heavy goods over long distances.
- Must maintain daily productivity with limited staff resources.

Solution & Insight

- ADLINK's RQX-59F can support various types of LiDAR and up to 8 FPD-Link III cameras. It processes sensor data in real-time and enables forklift robots to navigate safely in narrow spaces, even with big and heavy cargo.
- A forklift robot can do the work of several workers and never get tired, reducing labor costs yet improving work efficiency.

Use Case

Next-Gen Logistics Automation

Project Purpose

- Growing demand for smarter and more flexible AGV systems.
- AMRs offering efficient solutions amid rising labor costs.
- Minimizing workplace injuries caused by incorrect machine handling.





Delivery Robot

Challenges & Requirements

- Ensuring safe and reliable automated navigation in dynamic and unpredictable environments
- Designing and integrating robust sensor systems for accurate perception and obstacle avoidance

Solution & Insight

- ADLINK's RQX-59G supports the integration of various sensors, such as cameras and LiDAR, and effectively collects and processes sensor fusion data for reliable navigation and obstacle detection in dynamic environments.
- ADLINK's RQX-59G has a wide temperature operating range, ensuring performance and reliable operation in summer heat.

Use Case

24/7 Automated Delivery Service

Project Purpose

- Increasing demand for contactless, efficient delivery.
- Fulfilling 24/7 delivery services while addressing labor shortages in the delivery industry.
- Cost-effective alternative to traditional delivery services.





Robotic Lawn Mower

Challenges & Requirements

- A reliable edge AI platform to control the robot and process sensor data in real-time.
- 360-degree perception to navigate optimally through different terrains and environments.

Solution & Insight

- The RQX-59F with Jetson AGX Orin enhances the robotic mower's precision by detecting and avoiding obstacles through powerful AI performance.
- The RQX-59F supports up to 8 FPD-Link III cameras to ensure 360-degree image coverage, with internal IMU sensors also helping with navigation.

Use Case

Effortless Lawn Care

Project Purpose

- Robotic lawn mowers can be equipped with automated safety features for emergencies to prevent accidents and injuries caused by human errors.
- Effortless lawn maintenance and consistent results are achieved as the robotic mower handles cutting, trimming, and mulching, leading to a well-maintained lawn year-round.

Diagram



Segmentation



Security Robot

Challenges & Requirements

- The robots should be able to issue visual, audio, and smoke warnings to suspicious individuals and apprehend perpetrators.
- The robot should be able to patrol public areas and address potential threats automatically. Plus, it should be able to react quickly.

Solution & Insight

- The RQP-T37 enables complex tasks like facial recognition and object detection and can also facilitate real-time data processing for quick decision-making.
- The RQP-T37 is a compact and energy-efficient device that significantly reduces power consumption in security robots.

Use Case

Automated Public Safety Patrol

Project Purpose

- Security robots can be programmed to follow specific routes and protocols, ensuring reliable coverage without distractions or human errors
- Security robots can handle real-time threats using the processed data received from various sensors, replacing human guards in hazardous environments.





Autonomous Vehicle

Challenges & Requirements

- Seamless integration of hardware and software components with robust middleware.
- Achieving precise synchronization between LiDAR and multiple automotive cameras is crucial.
- Advanced computing is necessary for safety measurements and monitoring.

Solution & Insight

- TIER IV has implemented an edge perception development kit for self-driving buses at airports and in crowded cities.
- The edge perception development kit includes ADLINK's ROScube RQX-58G controller and TIER IV's C1/C2 cameras.
- ADLINK's RQX-58G excels in supporting sensor fusion data processing and simultaneously supporting up to 8 automotive GMSL2 cameras.

Note: To learn more about the Edge Perception Development Kit, please visit: https://www.adlinktech.com/en/autonomous-driving-visual-perception-tier-iv. We highly recommend upgrading the RQX-58G to the latest RQX-59G model for 8X stronger AI performance with the Jetson Orin module.

Use Case

The Future of Public Transit

Project Purpose

- Autonomous vehicles are equipped with advanced sensors and artificial intelligence, reducing human errors and accidents caused by distractions, fatigue, or impaired driving.
- Autonomous vehicles can communicate with each other and optimize traffic flow, leading to smoother and more efficient transportation systems.



Product Selection Guide





Model Name	RQX-59 Series					
NVIDIA [®] or Intel [®]	NVIDIA [®] Jetson AGX Orin™					
iMSL2 / FPD-Link III enabled	GMSL2 x 8 /FPD-Link III x 8					
Frame Sync and Time Sync	Yes					
Validated Sensors	GMSL2	FPD-Link III	Lidar			
	Tier IV: Automotive HDR camera C1/C2					
	Leopard: LI-AR0233-GMSL2	oToBrite: oToCAM264ISP	OS1-32			
	Leopard: LI-AR0820-GMSL2					
	oToBrite: oToCAM264ISP					
	oToBrite: oToCAM260ISP	oToBrite: oToCAM222				
	Sensing: SG8-OX08BC-5300- GMSL2					
OS	Jetpack 5.1.2 or above Ubuntu 20.04					
I/O	4x USB3.2; 2 x lockable USB3.2; 1x Micro USB (OTG); 2 x GbE					
Storage Device	1x M.2 Key M 2280 and 2242; 1x micro SD card slot					
Expansion	1x M.2 Key E 1630/2230 for Wi-Fi 6/BT; 1x M.2 Key B 3042/3052 for 5G/LTE					
Audio	Input/ Output					
CAN bus	CAN FD					
Dimensions	190 x 210 x 80 mm, 7.48 x 8.27 x 3.149 in (W x D x H) With expansion: 322 x 210 x 80 mm, 12.68 x 8.27 x 3.149 in (W x D x H)					
Weight	3.4kg w/o expansion box 4.7kg w/ expansion box					







Model Name	RQX-580/58G		RQP-T33/35/37		RQI-53/55/57/58	
NVIDIA [®] or Intel [®]	NVIDIA® Jetson AGX Xavier™		11th Gen Intel® Core™ i7/i5/i3		8/9th Gen Intel® Core™ i7/i5/i3	
GMSL2 / FPD-Link III enabled	GMSL2 x 8		USB camera		USB camera	
Frame Sync and Time Sync	Yes		Yes		Yes	
Validated Sensors	GMSL2	LIDAR	USB camera	LIDAR	USB camera	LIDAR
	Tier IV: Automotive HDR camera C1/C2	Ouster OS1-32	Intel Realsense D435	Ouster OS1-32	Intel Realsense D435	Ouster OS1-32
	Leopard: LI-AR0233- GMSL2					
	Leopard: LI-AR0820- GMSL2			SICK nanoScan3		
	oToBrite: oToCAM264ISP					SICK nanoScan3
	oToBrite: oToCAM260ISP					
OS	Jetpack 4. Ubunti	6 or above J 18.04	Compatible with Ubuntu 20.04		Compatible with Ubuntu 20.04	
I/O	4x USB3.2; 2 x lockable USB3.2; 1x Micro USB (OTG); 2 x GbE		2x USB 3.2 Gen2 Type A port;2x USB 3.2 Gen2 Type C ports; COM 1: RS-232; COM 2: power management; 1x 1GbE, 1x 2.5GbE; 1x DP, 1x HDMI		4x GbE; COM 1/2: RS-232/422/485; 6 x USB 3.1 Gen 1 Type A; 4x USB 2.0 Type A	
Storage Device	1x M.2 Key M 2280 and 2242; 1x micro SD card slot		t 1x M.2 Key-M for NVMe PCIe Gen4 x4 SSD		256GB mSATA SSD or 128GB mSATA SSD or 64GB mSATA SSD	
Expansion	1x M.2 Key E 1630/2230 for Wi-Fi 6/BT; 1x mini PCIe socket for 4G/LTE		1x M.2 Key-E 2230 for Wi-Fi		1 x Mini PCle for CAN; 1 x Mini PCle for WiFi or LTE; 1 x A+E key, 2230 for Wi-Fi	
Audio	Input/ Output		Input/ Output		N/A	
CAN bus	CAN FD		N/A		CAN FD module (FARO-FP900) (optional)	
Dimensions	190(W) x 210(D) x 80(H) mm (7.48 x 8.27 x 3.149 inch) With Expansion: 322(W) x 210(D) x 80(H) mm (12.68 x 8.27 x 3.149 inch)		:h) 140 (W) x 110 (D) x 63 (H) mm		w/o expansion box: 210(W) × 240(D) × 86(H) mm; w/ expansion box: 210(W) × 240(D) × 165(H) mm	
Weight	3.4kg w/o expansion box 4.7kg w/ expansion box		1,0	86g	3.6kg w/o e> 4.6kg w/ ex	pansion box pansion box

ADLINK Technology, Inc.

No. 66, Huaya 1st Rd., Guishan Dist., Taoyuan City 333411, Taiwan Tel : +886-3-216-5088 Fax : +886-3-328-5706

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Worldwide Offices

Ampro ADLINK Technology, Inc.

6450 Via Del Oro, San Jose, CA 95119-1208, USA Tel: +1-408-360-0200 Toll Free: +1-800-966-5200 (USA only) Fax: +1-408-360-0222 Email: info@adlinktech.com

ADLINK Technology (China) Co., Ltd.

上海市浦东新区张江高科技园区芳春路 300 号 (201203)

300 Fang Chun Rd., Zhangjiang Hi-Tech Park Pudong New Area, Shanghai, 201203 China Tel: +86-21-5132-8988 Fax: +86-21-5192-3588 Email: market@adlinktech.com

ADLINK Technology Beijing

北京市海淀区上地东路 1 号盈创动力大厦 E 座 801 室 (100085) Rm. 801, Power Creative E, No. 1 Shang Di East Rd. Beijing, 100085 China Tel: +86-10-5885-8666 Fax: +86-10-5885-8626 Email: market@adlinktech.com

ADLINK Technology Shenzhen

深圳市南山区科技园南区高新南七道数字技术园 A1 栋 2 楼 C 区 (518057) 2F, C Block, Bldg. A1, Cyber-Tech Zone, Gao Xin Ave. Sec. 7 High-Tech Industrial Park S., Shenzhen, 518054 China Tel: +86-755-2643-4858 Fax: +86-755-2664-6353 Email: market@adlinktech.com

ADLINK Technology Singapore Pte. Ltd.

84 Genting Lane #07-02A, Axxel Innovation Centre, Singapore 349584 Tel: +65-6844-2261 Fax: +65-6844-2263 Email: singapore@adlinktech.com

ADLINK Technology Singapore Pte Ltd. (Indian Liaison Office)

#50-56, First Floor, Spearhead Towers Margosa Main Road (between 16th/17th Cross) Malleswaram, Bangalore - 560 055, India Tel: +91-80-42246107, +91-80-23464606 Fax: +91-80-23464606 Email: india@adlinktech.com

ADLINK Technology Japan Corporation

〒 101-0045 東京都千代田区神田鍛冶町 3-7-4 ユニゾ神田鍛冶町三丁目ビル 4F Unizo Kanda Kaji-cho 3 Chome Bldg. 4F, 3-7-4 Kanda Kajicho, Chiyoda-ku, Tokyo 101-0045, Japan Tel: +81-3-4455-3722 Fax: +81-3-5209-6013 Email: japan@adlinktech.com

〒 450-0002 愛知県名古屋市中村区名駅 5-31-10 リンクス名駅ビル 3F LINKS Meieki Bldg. 3F, 5-31-10 Meieki, Nakamura-ku, Nagoya-city, Aichi 450-0002, Japan Tel: +81-52-589-9018 Fax: +81-52-583-2807 Email: japan@adlinktech.com

ADLINK Technology Korea Ltd.

경기도 용인시 수지구 신수로 767 A 동 1503 호 (동천동 , 분당수지유타워) (우) 16827 A-1503, U-TOWER, 767 Sinsu-ro, Suji-gu, Yongin-si, Gyeonggi-do, Republic of Korea, 16827 Toll Free:+82-80-800-0585 Tel: +82-31-786-0585 Fax: +82-31-786-0583 Email: korea@adlinktech.com

ADLINK Technology, Inc. (Israel Liaison Office)

MIXER Herzliya (Building B, 9 Floor) 3 Arik Einstein st., Zip code 4610301 Herzliya, Israel, P.O.Box - 351 Tel: +972-54-632-5251 Fax: +972-77-208-0230 Email: israel@adlinktech.com

ADLINK Technology GmbH

Hans-Thoma-Straße 11 D-68163 Mannheim, Germany Tel: +49 621 43214-0 Fax: +49 621 43214-30 Email: germany@adlinktech.com

Ulrichsbergerstraße 17 D-94469 Deggendorf, Germany Tel: +49 991 290 94–10 Fax: +49 991 290 94–29 Email: germany@adlinktech.com

ADLINK Technology, Inc. (French Liaison Office)

Bâtiment Thalès - Parc des Algorithmes, Route de l'Orme des Merisiers, 91190 SAINT AUBIN, France Tel: +33 (0) 1 60 12 35 66 Fax: +33 (0) 1 60 12 35 66 Email: france@adlinktech.com

ADLINK Technology, Inc. (UK Liaison Office)

First Floor West Exeter House, Chichester fields Business Park Tangmere, West Sussex, PO20 2FU, United Kingdom Tel:+44-1243-859677 Email: uk@adlinktech.com





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